The industry's first truly universal N Scale decoder that is at home on all NMRA DCC systems. The characteristics of the decoder are:

- * Selectable for operation with 14/27, 28/55, 128 direct drive or 128 speed table mode with precision glide motor control.
- Two on/off function outputs with a current rating of 100 mA that can be configured for either directional lighting, full Rule 17 lighting, or lights and F1
- Headlights can also be dimmed using an extra function.
- Support for Advanced Consist Control and Extended Addressing
- Operation on conventional DC layouts is possible. This feature may be disabled.
- Full Support for operations mode programming (long and short) and full support for all forms of programming as described in NMRA RP-9.2.3
- * Rich set of properties which the user can set to customize the decoder to a particular locomotive.
- * Provides 0.5A continuous motor current.
- * Size L 0.53" x W 0.37" x H 0.13" L 13.6mm x W 9.5mm x H 3.3mm

LE077XF Micro DCC Decoder

Art. No. 10077 Version 4.5 Revised 8/00







The LE077XF Micro Decoder

The LE077XF represents a whole new concept to the evolution of DCC. Not only is the LE077XF designed to use with our own DIGITAL plus system, it is also designed to be at home on all the other popular NMRA DCC systems. To accomplish this we first designed a decoder to be in full conformance to the NMRA Standards and RPs and then augmented the decoder to work well with all other major systems on the market.

Although the LE077XF has a low price, it is packed with all the features you expect in a high end decoder. Independent or directional lighting (that can be dimmed using a function), advanced consist control, extended addressing, operations mode programming and full support for all the various speed step modes including 128 step motor control, are but a few examples of the advanced features found in the LE077XF.





The NMRA awards its prestigious C&I label to products it has tested and found to be in full compliance with all NMRA DCC Standards, Recommended Practices and industry norms. The LE077XF decoder has been awarded an NMRA C&I Warrant.

Many characteristics of the LE077XF decoder can be programmed to customize the decoder to its locomotive. Please read "The Configuration Variables and Their Meanings" section later in this booklet for details on the configuration variables supported by the LE077XF. The LE077XF supports all forms of programming described in NMRA Recommended Practice 9.2.3 including the user friendly direct CV programming mode and the operations mode programming so that you can adjust values while the locomotive is in use. For example, you can operate the decoder with the factory pre-set speed table or generate your own. You can set which end of the locomotive is the forward end. You can even decide whether or not you want to be able to operate on conventional DC layouts.

Preparing to Install the LE077XF

The locomotive must be tested for excellent operation on normal DC power before installing the decoder. Replace worn out motor brushes and burned out light bulbs. Clean any dirt or oxidation from the wheels and pickups, and make sure that electrical contact is smooth. Now is also a good time to lubricate your locomotive. A locomotive that runs well under DC will run exceptionally well under DCC.

Take note which motor brush is connected to the right rail and which to the left rail. This information allows you to connect the decoder to the motor with the correct polarity.

The LE077XF is quite small and will fit into most N locomotives even those with narrow hoods.

Some advice on the current draw of the decoder output:

The current for all the decoder outputs is supplied by an internal rectifier with a maximum current rating of 0.7 Amps. The sum of all currents to the motor and the function outputs cannot exceed this limit. Each individual output can only draw up to it's limit.

Summing up the individual current limits leads to a number larger than 0.7 Amps., but they still are not permitted to draw more than this limit.

Example:

Suppose the motor may require as much as 0.5 A continuously. Then the function outputs combined must not exceed 0.2 A.

Some advice on installing the decoder:

Although the LE077XF has many internal safeguards to prevent damage, you must not allow any metal part of the locomotive to touch the surface components of the decoder. This could cause a direct internal short circuit and the decoder will be destroyed.

DO NOT WRAP decoder with electrical tape or shrink wrap!

Doing so will impede air circulation and degrade the performance of the decoder. Instead, put electrician tape over any part of the locomotive frame or body that might touch the decoder and use double sided foam mounting tape to mount the decoder. This will prevent short circuits without 'suffocating' the decoder.

The existing shrink wrap over a part of the locomotive decoder protects static sensitive parts and must not be removed. After disconnecting the wiring from the motor brushes, the brushes MUST be isolated from the rail pickup. Achieving isolation may require some different approaches on different locomotives, perhaps unsoldering wires, placing a thin piece of insulating plastic between brush terminal and contact spring. In other words, after isolation, there must be NO electrical contact between the motor and the rail pickup. If you have a VOM, check for infinite resistance between the motor and all the wheels. Take special note that metal contact might occur only when the loco body is reinstalled.

The LE077XF can not be set up for simultaneous use for 2-rail pickup and overhead cantenary or trolley operation. If the locomotive is turned the wrong way, the decoder could get twice the track voltage which would destroy it!

Wiring Options

There are two wiring options for installing the LE077XF, depending on how the locomotive is constructed. The two functions could be connected with their common to the track voltage as shown in Figure 1, or, use the decoders floating common as shown in Figure 2. A mixture of both options is also possible. Note that both Rule 17 and traditional reversing headlights are supported.

If the bulbs for the headlights are floating (isolated against wheel pick up and chassis) and connected according to Figure 2, they will shine brighter compared to the option shown to Figure 1. Furthermore, the directional headlights will function while operating on conventional DC layouts.

Step by Step Installation

Two wires connect the decoder to the motor. Make sure that the motor is electrically isolated from both track pickups: NMRA Socket

- Orange wire to the motor terminal that was previously connected to the right rail (Pin #1).
- Gray wire to the motor terminal that was previously connected to the left rail (Pin #5).

Two wires connect the decoder to the track electrical pickups:

- Red wire to right rail pickup (Pin #8).
- Black wire to the left rail pickup (Pin #4).

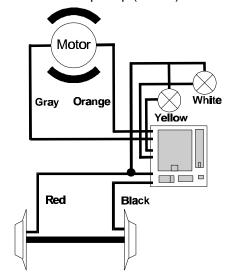


Figure 1: Wiring the LE077XF using track voltage common

Three wires connect the headlights and functions to the decoder:

- White wire (Pin #6) to the forward headlight. If the bulb is isolated, connect the blue wire (Pin #7) to the other terminal.
- Yellow wire (Pin #2) to the rear headlight or F1 depending on CV52 bit 0. If the bulb or function is isolated, then connect the blue wire (Pin #7) to the other terminal.

Place the locomotive (without the body) on the programming track and read back the locomotive's address from the decoder. If the

decoder is properly installed, you will be able to read back the factory pre-set address 03. Remove the locomotive from the track, and if necessary correct any wiring errors.

If the bulbs are isolated, connect the blue wire to their common point as shown in Figure 2. Now you are ready to program the locomotive address and begin test running.

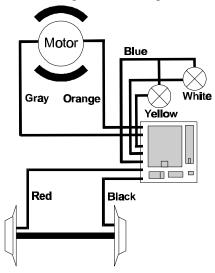


Figure 2: Wiring the LE077XF using a floating common.

Programming the locomotive decoder LE077XF

Many features such as the locomotive's address, acceleration and configuration can be customized to the individual locomotive that the decoder is installed in. The properties will be saved in non-volatile memory locations on the locomotive decoder so they retain their value even after the power has been removed for years. The values are set electronically which means that the locomotive does not need to be opened after initial installation of the decoder to read or later modify any CV value. These memory locations are called "Configuration Variables, or CVs" by the NMRA. The LE077XF has a total of 128 CVs. Not all of them are used at this time as many are reserved for future use.

Any NMRA DCC Command Station, such as the DIGITAL plus LZ100 and a Hand Held LH100, LH200 or an Interface LI100, can

be used to program the locomotive decoder LE077XF. With several entry level systems such as the ROCO 'DIGITAL is cool' command station, only CV #1 (locomotive address) can be set unless you use a separate programmer. More advanced DCC systems support the ability to set many more CVs. The LE077XF supports all modes and can be programmed by all NMRA DCC programmers. Specific details for reading and writing the decoder's configuration variables can be found in the manuals of the appropriate equipment.

The configuration variables and their meaning

The following table lists the various CVs supported in the LE077XF decoder. Both the New CV numbers and the older Register numbers are provided for cross reference.

Please note: Some CVs (such as CV29) have specific meanings for each bit. The bit assignments in this table use a bit numbering scheme of 0-7 to correspond the NMRA convention for universal bit numbering. DIGITAL plus LH100 and LH200 handhelds use a scheme of 1-8 to refer to the individual bits rather than 0-7. (Bit 0 in this table is displayed as a"1" on LH100 handheld, Bit 1 is identified as "2"...)The bit numbers in () within these tables contain the LH100 and LH200 bit numbers.

Table 1: LE077XF Configuration Variables

CV	R	Description	Range	Factory
	е			setting
	g			
1	1	Locomotive address:	1-127	3
		This is the number with which you select a		
		locomotive in the DIGITAL plus system.		
		Setting the address from #1 to #3 using register		
		mode will reset the decoder to utilize 14 speed		
		step operation.		
2	2	Start voltage:	0-31	8
		This is the voltage applied to the motor in speed		
		step 1. Set this value so that the locomotive just		
		starts moving in speed step 1.		

^{**}Note: in the factory setting field the numbers in the [] are decimal.

CV	R	Description		Setting
3	3	Acceleration Momentum:	1-31	1
		Determines the rate of change of speed upon		
		acceleration. A higher value leads to a slower		
		acceleration.		
4	4	Brake Momentum:	1-31	1
		Determines the rate of change of speed upon		
		braking. A higher value leads to longer brake		
		distance.		
-	5	Contains CV29 (see CV29 below)	0-55	6
-	6	Page Register:	0-127	1
		Normally this CV is not modified directly by a		
		user. For correct operation, this CV should be		
		set to have a value of 1 after any use.		
7	7	Version Number:	-	45
		This location stores the version number of the		
		decoder. This location is read only.		
8	8	Manufacturers Identification / Factory reset	-	99
		This value is the manufacturer ID of the decoder,		
		(Lenz =99). Writing a value of 33 using Register		
4-		mode resets all CVs to their factory condition	400	
17	-	Extended Address High Byte	192-	0
40		Potential Address Less Bots	231	
18	-	Extended Address Low Byte	0-255	0
		The two byte address if used is contained in CV17+18		
19	Coi	nsist Address	0-255	0
	The	advanced consist address if used is stored in		
	CV	19		
23	Acc	celeration Trim This Configuration Variable	0-255	255
	con	tains additional acceleration rate information that		
	is to	be added to or subtracted from the base value		
	contained in CV3			
24	Deceleration Trim This Configuration Variable		0-255	255
	contains additional braking rate information that is to			
	be added to or subtracted from the base value			
		tained in CV4		
29	Decoder Configuration, Byte 1:		0-55	6
	Several decoder properties are set with this byte.			
		anges are easiest if done in binary mode, but can		
		be done by adding the decimal () for all the		
		ures desired together and writing the total into		
	CV29. The detailed properties are:			

CV	Descr	iption	Range	Setting
29	bit 0	locomotive direction:	0,1	0
	Locomotive's relative direction: This bit sets			
	(1)	the direction the locomotive will move when		[1]
		told to move forward in digital mode.		
		0 = locomotive's direction is normal		
		1 = locomotive's direction is inverted		
	bit 1	Headlight mode:	0,1	1
		0 = Operation with 14 or 27 speed step		
	(2)	systems. This setting is selected when the		
		locomotive decoder is used with any Digital		[2]
		system that does not support 28 speed step		
		mode. If the headlights turn on and off as the		
		speed is increased, the command station is		
		configured for 28 speed step mode, and the		
		decoder is in 14 speed step mode. 1 = Operation with 28, 55 or 128 speed steps.		
		If you use this setting, the Command Station		
		must also be configured to use 28 speed step		
		mode or 128 speed step mode for the		
		decoder's address, otherwise the headlights		
		can not be controlled.		
	bit 2	Usage on conventional DC layouts:	0,1	1
	Dit Z	0 = locomotive operates in digital mode only	0,1	
	(3)	1 = locomotive can operate on either		[4]
	(-)	conventional DC and on DCC		[.]
	bit 3	always 0	0	0
	bit 4	Speed Curve Selection:	0,1	0
		0 = factory pre-set speed curve is used	-,	
	(5)	1 = user defined speed curve is used. Please		[16]
	, ,	enter the appropriate values into CV 67 to 94		
		before setting this bit.		
	bit 5	Extended Addressing:	0-1	0
	(6)	0= Normal addressing		
		1=Two Byte extended addressing		[32]
	bit 6	always 0	0	0
	bit 7			
50		Decoder Configuration, byte 2:		0
	Similar to CV 29, but used to set other properties			
	bit 0 not used			
	bit 1	0 = CV23 and CV24 are not active	0,1	0
	(2)	1 = CV23/CV24 are active and contain the		[2]
		acceleration and deceleration trim values		
		that are added to CV3 or CV4.		

CV	Desc	ription	Range	Setting
50		Brake momentum on DC operation.		0
	bit 2	Used to achieve prototypical braking at red signal		
		indications if conventional DC control CV29.2 is		(4)
	(3)	disabled. (CV 29 bit $2 = 0$)		
		0 = locomotive proceeds with track voltage		
		dependent speed inside the conventional DC		
		section.		
		1 = locomotive brakes in the conventional DC		
	1 '' 0	section with pre set brake momentum.		
	bits 3			
51		ing Special Effects for Outputs A and B		0
	bit 0	0 = the headlights are directional.	0,1	0
		1 = the lights are independent per Rule 17. F0		
	(1)	controls the front headlight and F1 the rear		[1]
		headlight or a separate function.		
	bit 1	0 = function dimming disabled	0,1	0
	(2)	1 = the value in CV52 is used for		[2]
		headlight/function dimming.		
	bit 2	1= if CV51.0 and CV51.1 both =1 (dimming and	0,1	0
	(3)	Rule17 are both active), F4 dims F0. If CV51.0 =		[4]
		0 and CV51.1 =1 (directional dimming) then F1		
		dims the forward headlight if on.		
	bit 3	1= if CV51.0 and CV51.1 both =1 (dimming and	0,1	0
	(4)	Rule 17 are both active), F4 dims F1. If CV51.0 =		[8]
		0 and CV51.1 =1 (directional dimming) then F1		
	1 4	dims the rear headlight if on.		
	bits 4			
52		ning CV - contains the value used for dimming. 0	0-255	64
- N		k 255 is max brightness	_	0 441
CV		scription	Range	Setting
67 to		ues for user defined speed curve:	0-255	Factory
94`		ese registers are used for a user defined speed		Default
		curve. The factory setting for these registers is shown		Speed
	in the following speed curve table. The value in eac CV determines the velocity of the locomotive for eac			Curve
		igned speed step:		
		the 14 speed step mode the odd CVs are used		
		ou are using 128 speed step mode and you have		
		activated the user defined speed table, the		
		intermediate speed steps are calculated by the		
		decoder.		
105		User Identification #1		255
106	Use	User Identification #2		255
128	Dec	Decoder Software Version – read only		01
		Table Tolling Tolling	l	<u> </u>

Creating a Speed Curve

One common feature is to set a specific operating speed curve for your locomotives. This is usually done to have dissimilar locomotives have the same performance characteristics or to have the locomotives perform more prototypically. Start by writing down how you want to assign the internal speed settings to the speed steps, for example by making up a table as shown below.

Note: CV2 (Start Voltage) is still used as part of the calculation even when the decoder is in User Defined Speed Curve mode.

Speed step in	Speed step in	Default speed	CV /
14/27 mode	28 mode	setting	register
1	1	4	67
	2	8	68
2	3	12	69
	4	16	70
3	5	20	71
	6	24	72
4	7	28	73
	8	33	74
5	9	38	75
	10	43	76
6	11	48	77
	12	53	78
7	13	60	79
	14	67	80
8	15	74	81
	16	82	82
9	17	90	83
	18	98	84
10	19	106	85
	20	115	86
11	21	125	87
	22	137	88
12	23	152	89
	24	178	90
13	25	194	91
	26	212	92
14	27	232	93
-	28	255	94

In 128 speed step mode the decoder internally averages the speed table to obtain the correct speed step value.

North American Warranty

Lenz GmbH does everything it can do to ensure that its products are free from defects and will operate for the life of your model railroad equipment. From time to time even the best engineered products fail either due to a faulty part or from accidental mistakes in installation. To protect your investment in Digital Plus products. Lenz GmbH offers a very aggressive 10 year Limited Warranty.

This warranty is not valid if the user has altered, intentionally misused the Digital Plus product, or removed the product's protection, for example the heat shrink from decoders and other devices. In this case a service charge will be applied for all repairs or replacements. Should the user desire to alter a Digital Plus Product, they should contact Lenz GmbH for prior authorization.

Year One: A full repair or replacement will be provided to the original purchaser for any item that that has failed due to manufacturer defects or failures caused by accidental user installation problems. Should the item no longer be produced and the item is not repairable, a similar item will be substituted at the manufacturers discretion. The user must pay for shipping to an authorized Lenz GmbH warranty center.

Year 2 and 3: A full replacement for any item will be provided that has failed due to manufacturer defects. If the failure was caused by accidental user installation or use, a minimal service charge may be imposed. Should the item no longer be produced and the item is not repairable, a similar item will be substituted at the manufacturers discretion. The user must pay shipping to and from the authorized Lenz GmbH warranty center during this portion of the warranty period.

Year 4-10: A minimal service charge will be placed on each item that has failed due to manufacturer defects and/or accidental user installation problems. Should the item no longer be produced and the item is not repairable, a similar item will be substituted at the manufacturers discretion. The user must pay shipping to and from the authorized Lenz GmbH warranty center during this portion of the warranty period.

Please contact your dealer or authorized Lenz GmbH warranty center for specific instructions and current service charges prior to returning any equipment for repair.

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This equipment complies with Part 15 of FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

C € Please save this manual for future reference!

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